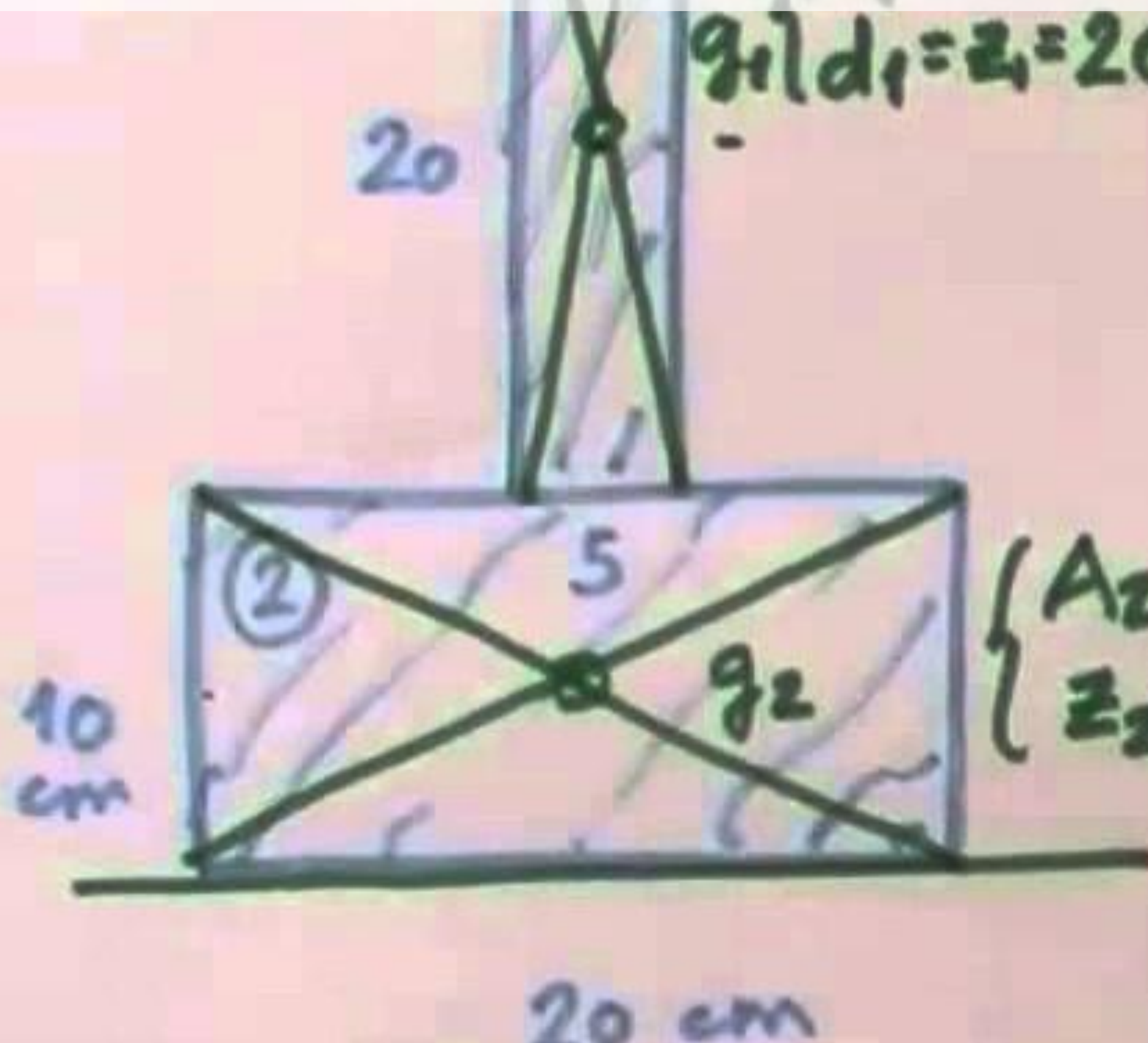


# LOAD INFLUENCE - CG



$A_1 = 100$   
 $g_1 | d_1 = z_1 = 20$

$$z_G = \frac{A_1 z_1 + A_2 z_2}{A_1 + A_2}$$

$A_2 = 200 \text{ cm}^2$   
 $z_2 = 5 \text{ cm}$

## Objectives of this unit

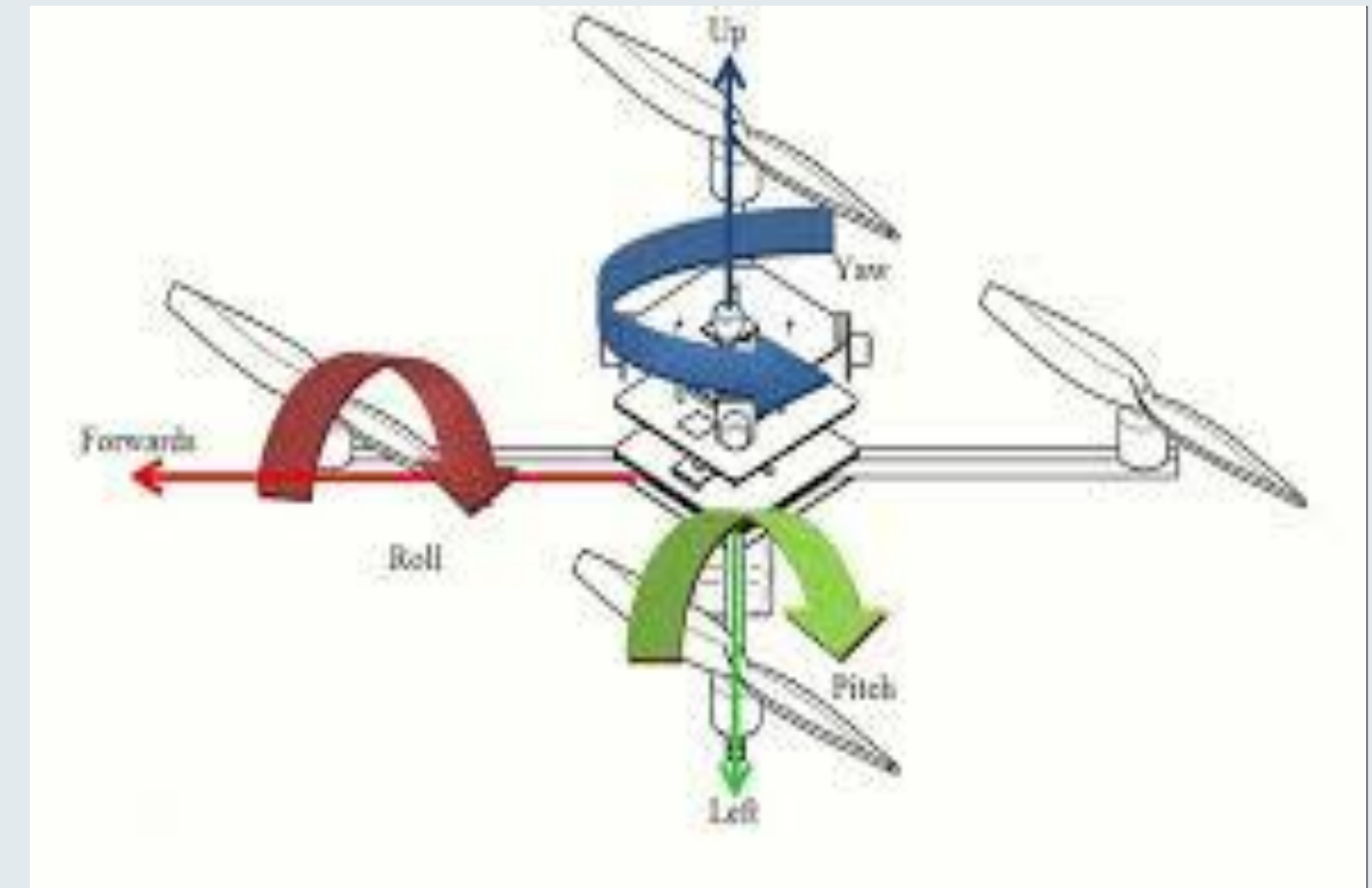
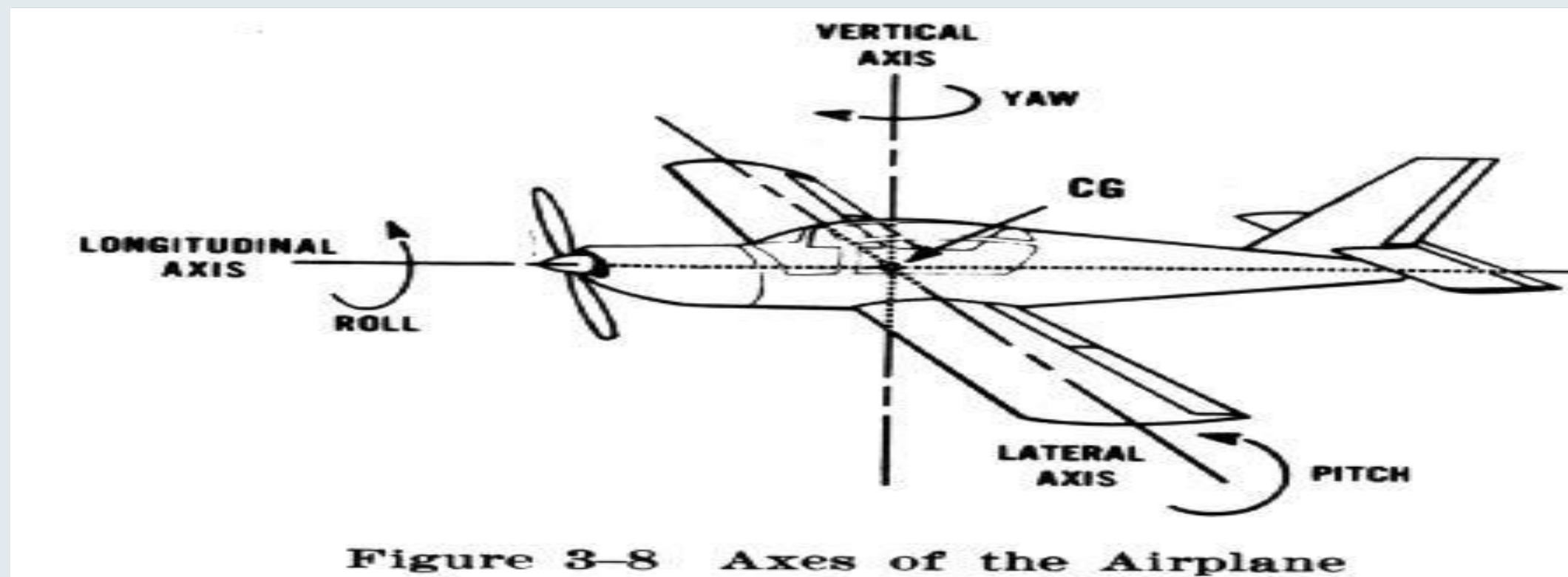
- Know the importance of weight and balance management for a safe and efficient operation. Know the basic data necessary to carry out the weighing and balancing process of a UAV. Identify the effects of loads and their locations on UAV behavior. Interpret the basic parts of a weight and balance sheet. Recognize the existence of critical differences between different classes of UAVs with respect to freight transport.

## Introduction

The following explanations are referenced to the generality of UAVs (rotary wing, fixed wing and aerostats). Their differences shall be specified, if necessary, in each case.

The correct weighing and balancing of the UAV will allow us to carry out an efficient and above all safe operation. This is because weight and roll directly affect: lift (produced by engines, propellers and/or wings), control and maneuverability (given by engines and/or control surfaces), take-off and landing distances (fixed-wing case), autonomy (time in flight or distance traveled), the flight height (service ceiling), the flight speeds (the heavier the UAV is), and the structure of the UAV (landing gear, arms, etc.).

## Initial concepts



## Conceptos iniciales

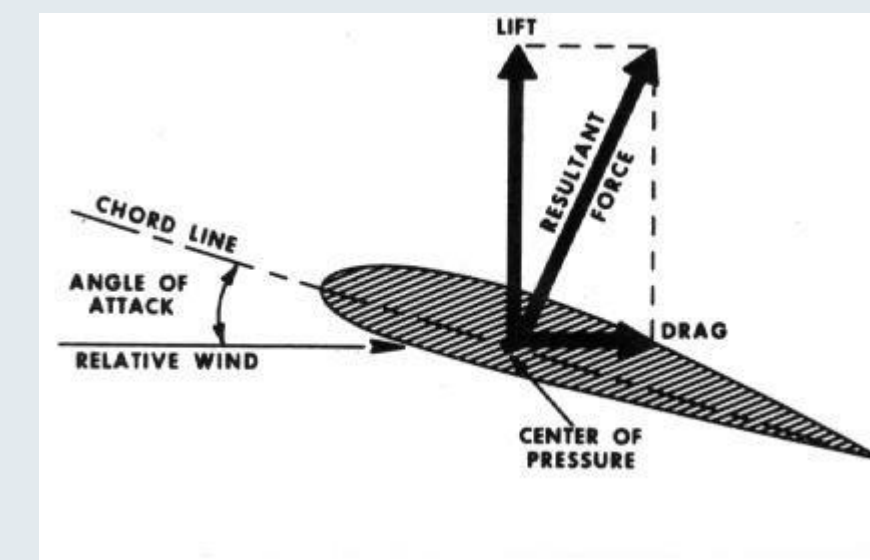
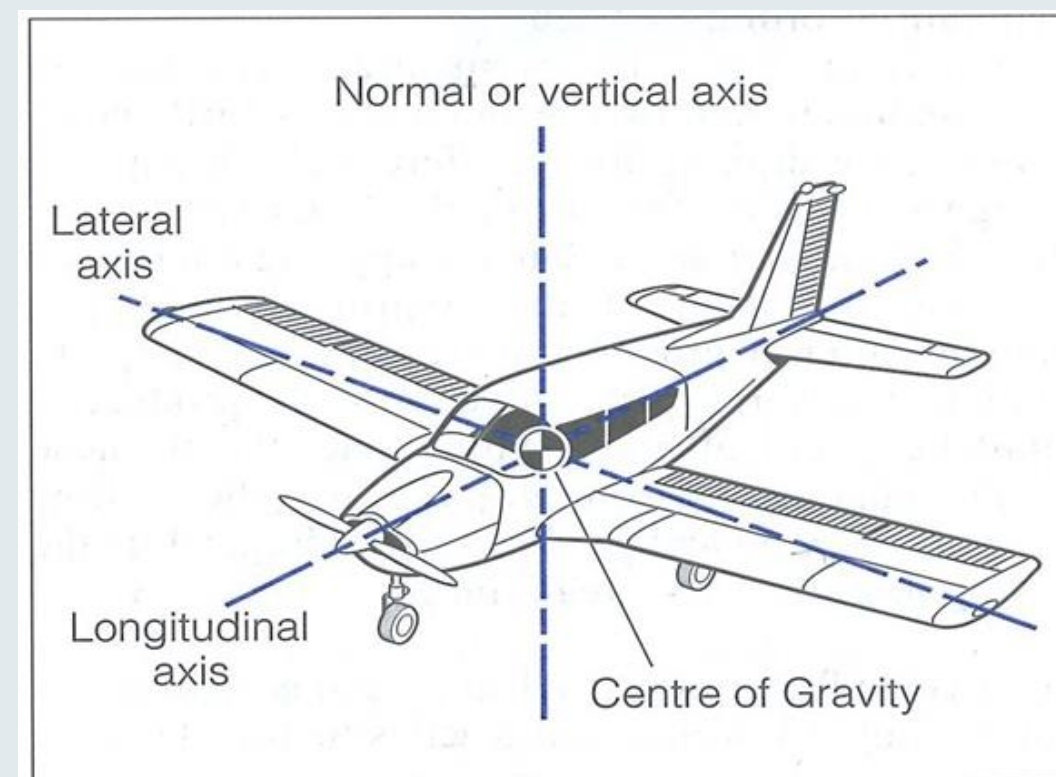
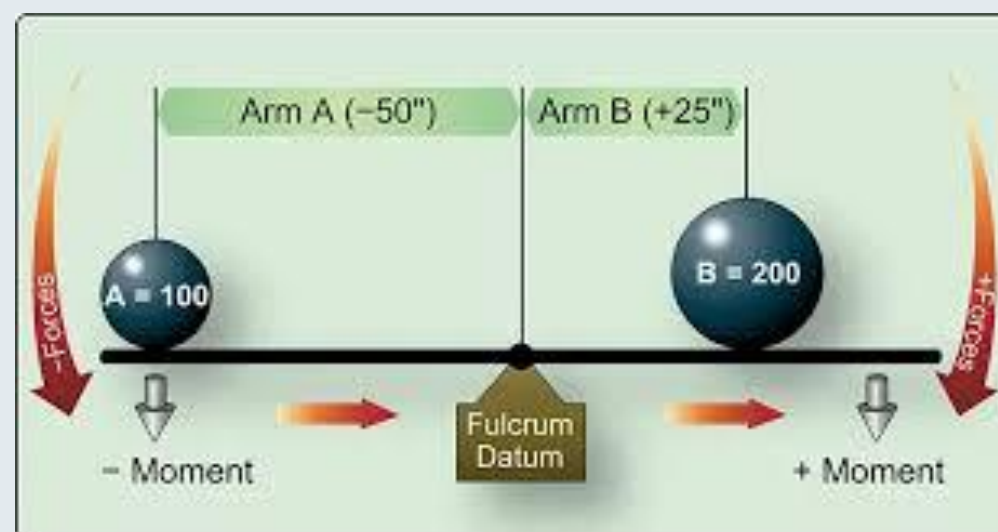
Reference line (Datum): Established by the manufacturer, it is used to calculate the distance from it to all the items that the UAV has.

Arm: It is the horizontal distance between an item in the UAV and the Reference Line (Datum).

Moment: Corresponds to the multiplication of the weight of an item of the UAV by its Arm.

Center of Gravity (CG): It is the theoretical point where the entire mass of the UAV is assumed to be concentrated. From which the device could be hung and it would remain static and in balance.

Center of Pressure (CP): It is the theoretical point where all the lifting force generated by the propellers or wings is considered applied.



## Conceptos iniciales

Weight empty (EW): Corresponds to the addition of weights of the structure, engines, propellers, and all the components operative that HE find fixed and of manner permanent in the UAV.

Payload (PL): It is all the load added to the Empty Weight (EW) of the UAV. As a container with parcel service either the fuel that HE requires for the operation (in the case of the UAV with engines to gasoline).

Maximum Weight Without Fuel (MZFW) \*: Corresponds to the maximum weight allowed taking into account all the items that will have either will load the UAV, without count with the fuel requested for the flight.

Weight Maximum Certificate of Takeoff (MCTOW): Is the weight maximum that can have the UAV to the moment of takeoff .

Weight Maximum of Landing (MLW): Weight maximum that will be able to have a UAV to the moment of the landing.

\* No used in UAV electrical.

# Calculations practical of Weight and Swinging

The calculation of weight and swinging will depend on each UAV specifically and by so much will be able to vary the items to be calculated, tables, graphs or procedures to arrive at the results. However, all will share data common, basics and extremely important for a safe operation:

## • Notes :

- Weight of the items as the EW and the PL.
- Arm of each one of the items (Yeah No were already included in the tables).
- Moments (Weight of the item - *multiplied* - Arm).

## • Summations :

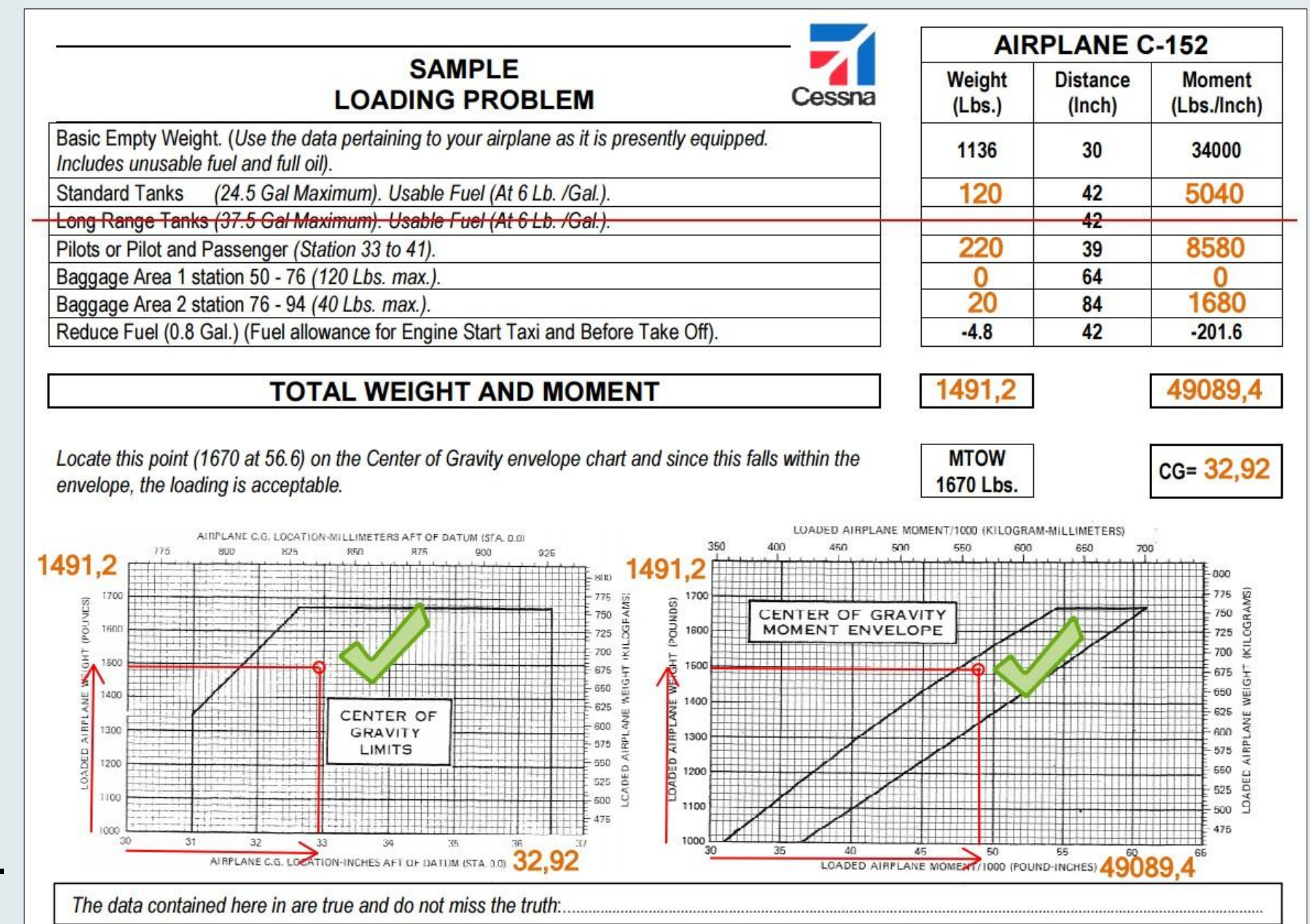
- Weights of the items, and as a result the Weight Total.
- Moments, gives as a result the Moment Total.

## • Calculation :

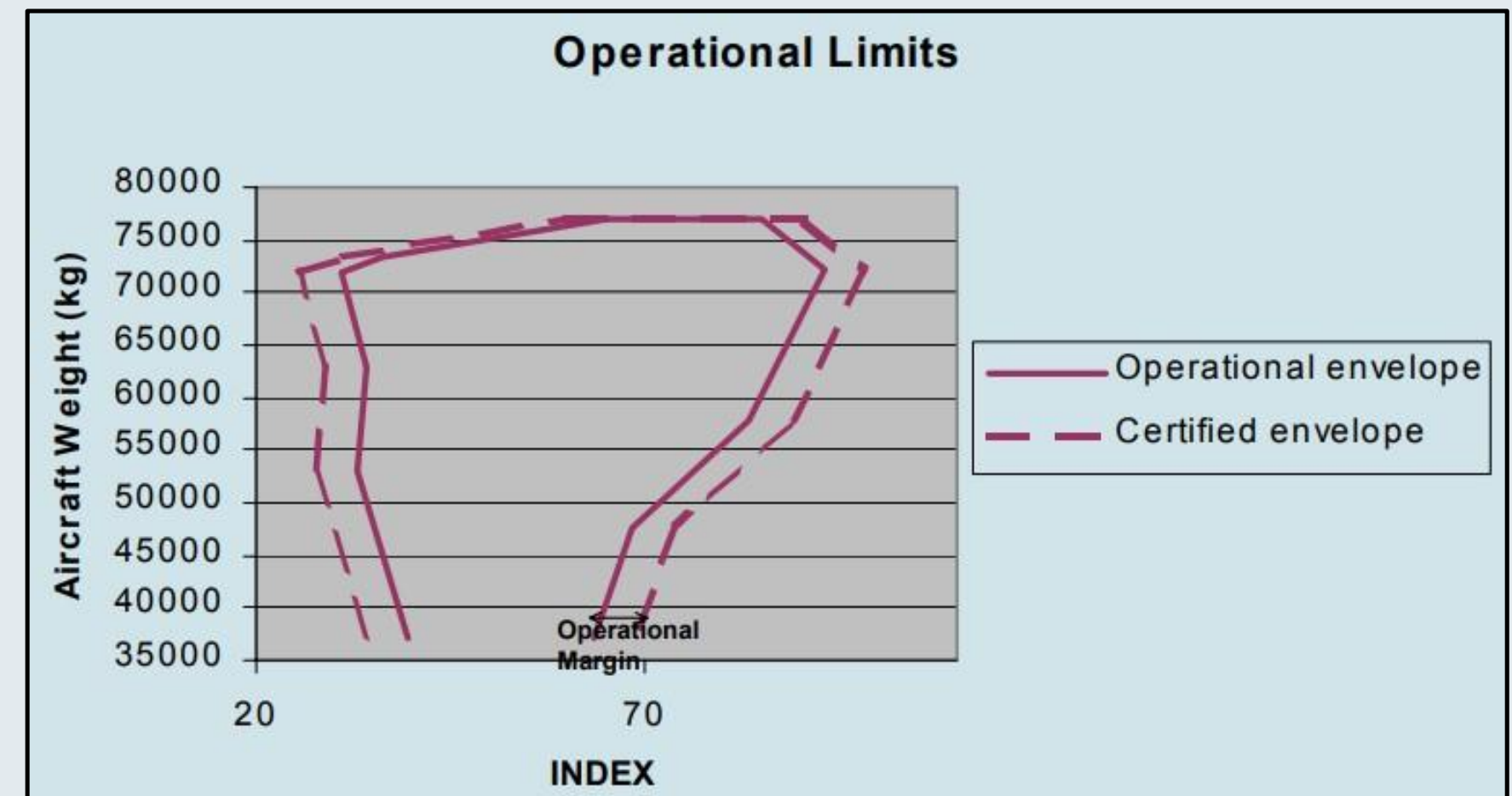
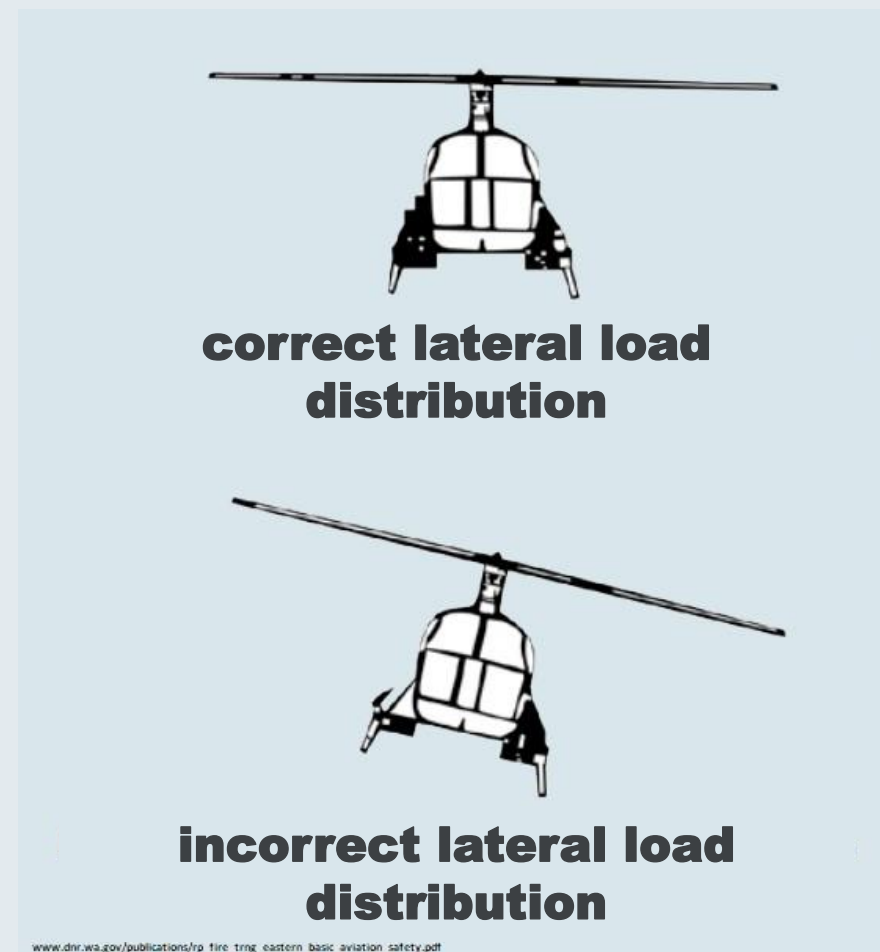
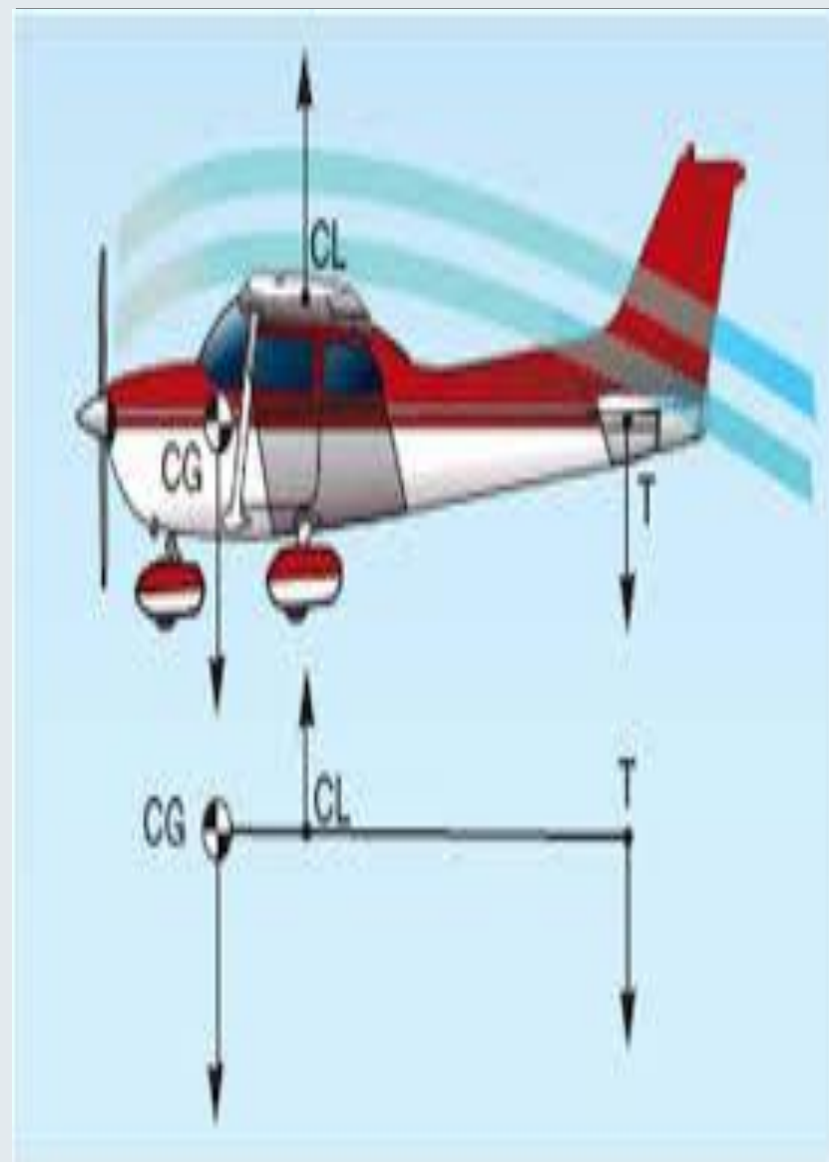
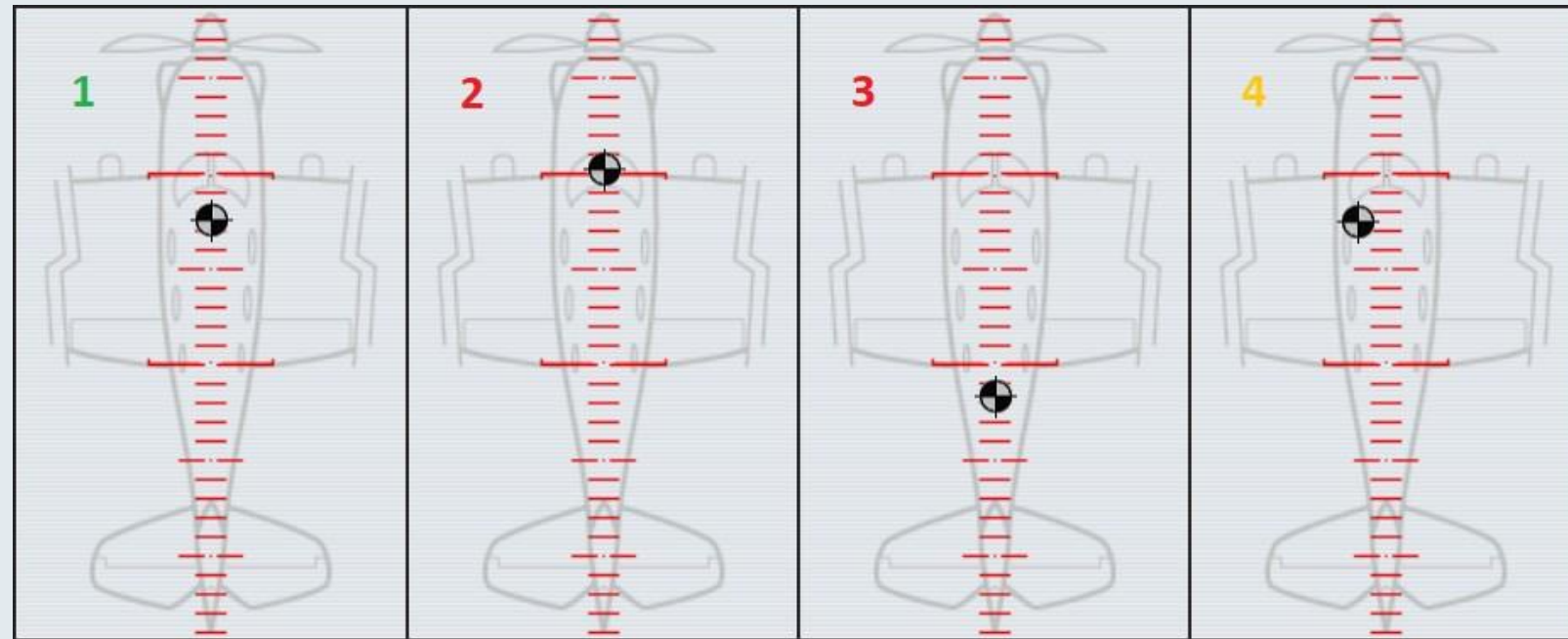
- CG (Moment Total - *divided* - Weight Total).

## • Checks :

- Don't get over the MCTOW.
- The CG I stayed inside of the boundaries certificates.



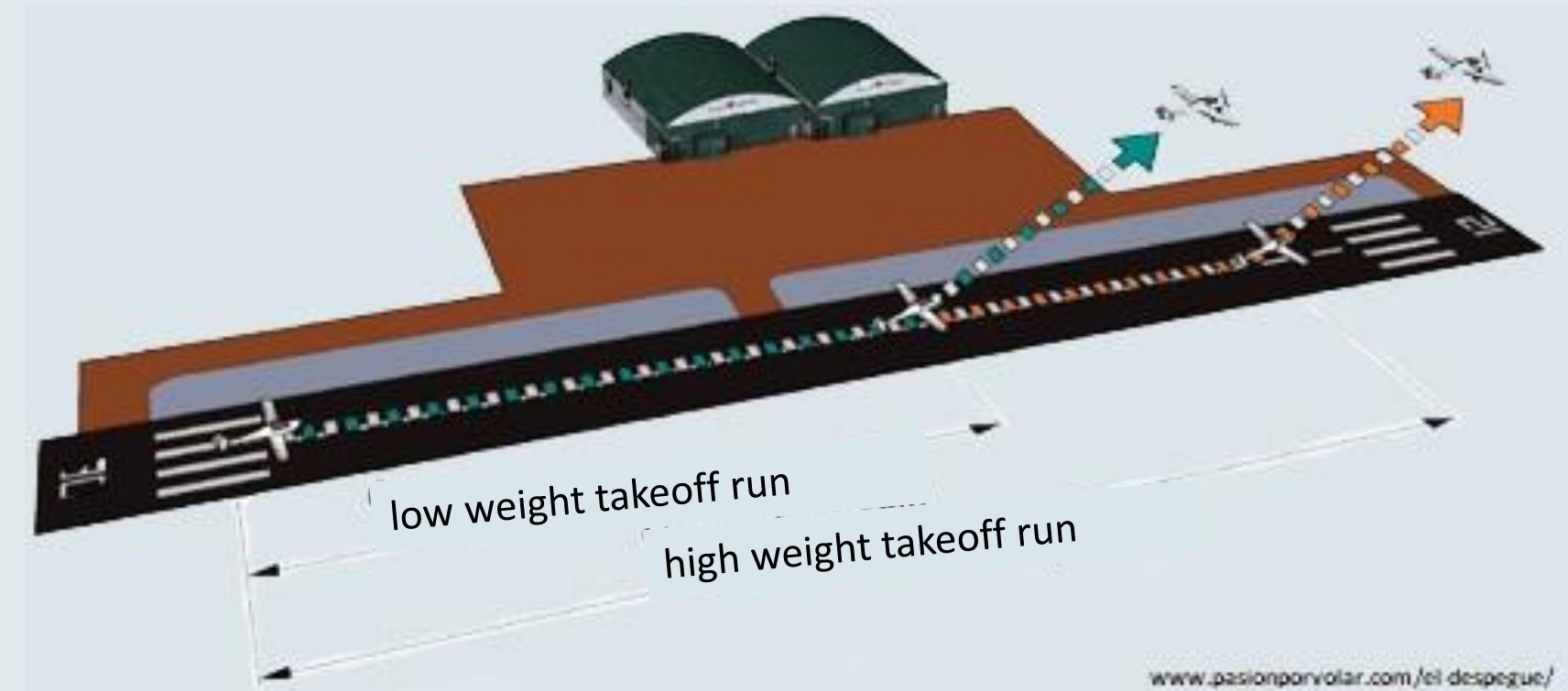
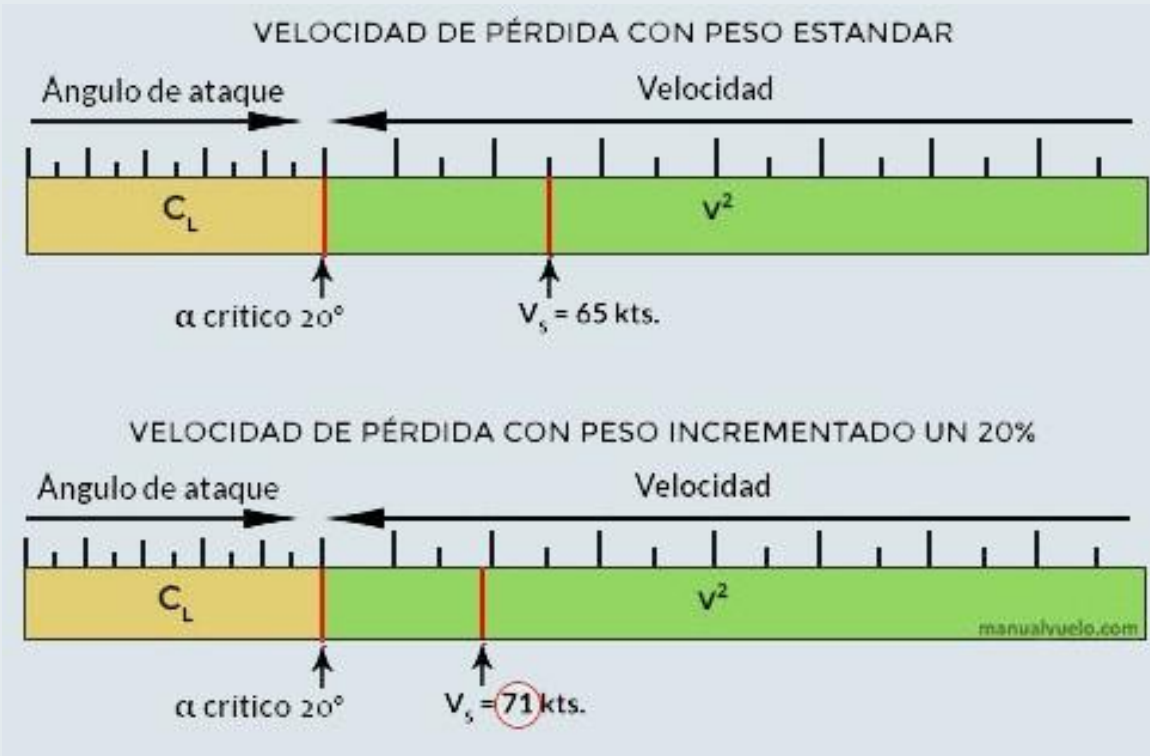
# Influence of the loads and his distribution about the performance and he control of the UAV



# Influence of the loads and his distribution about the performance and he control of the UAV

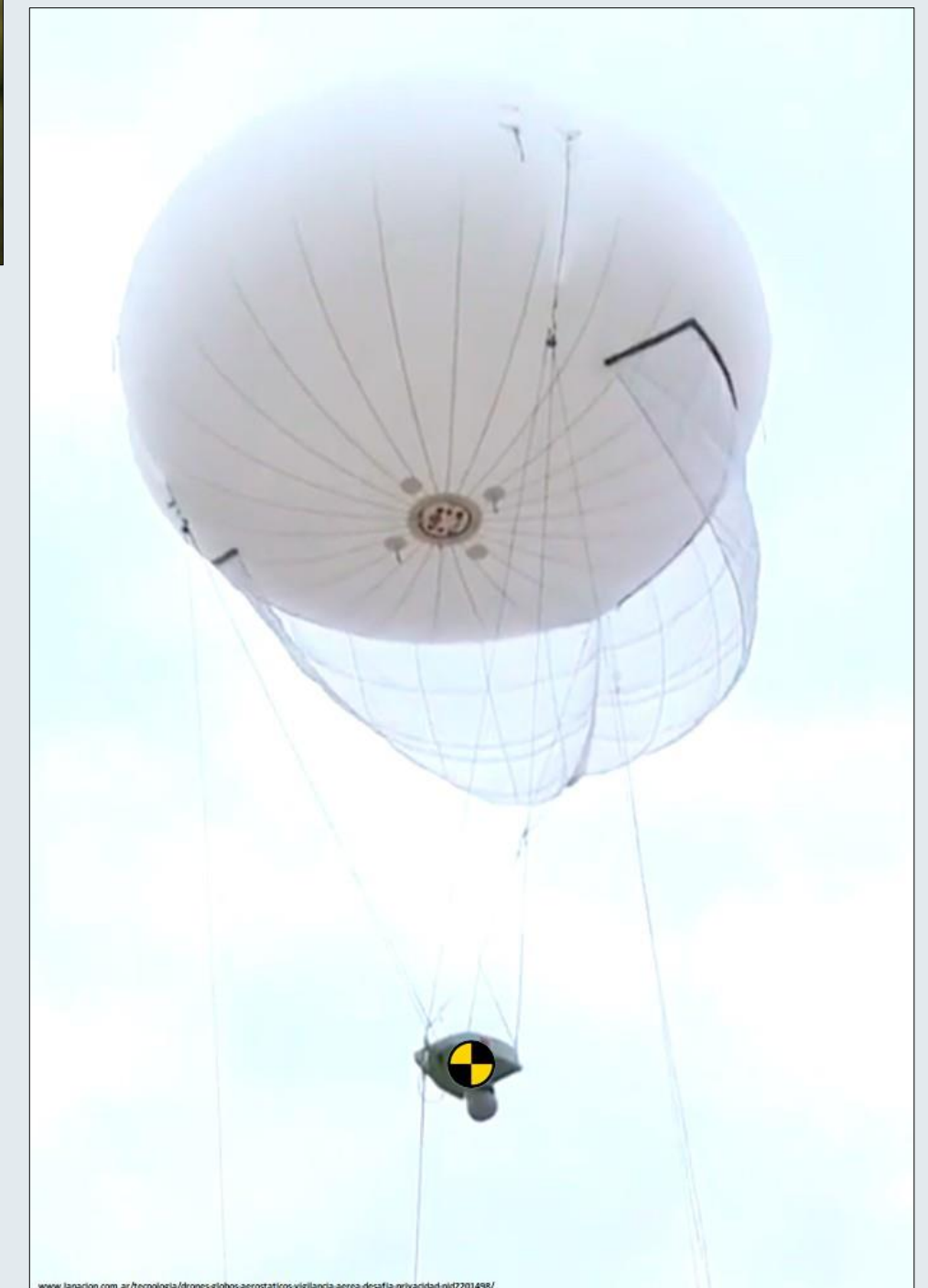
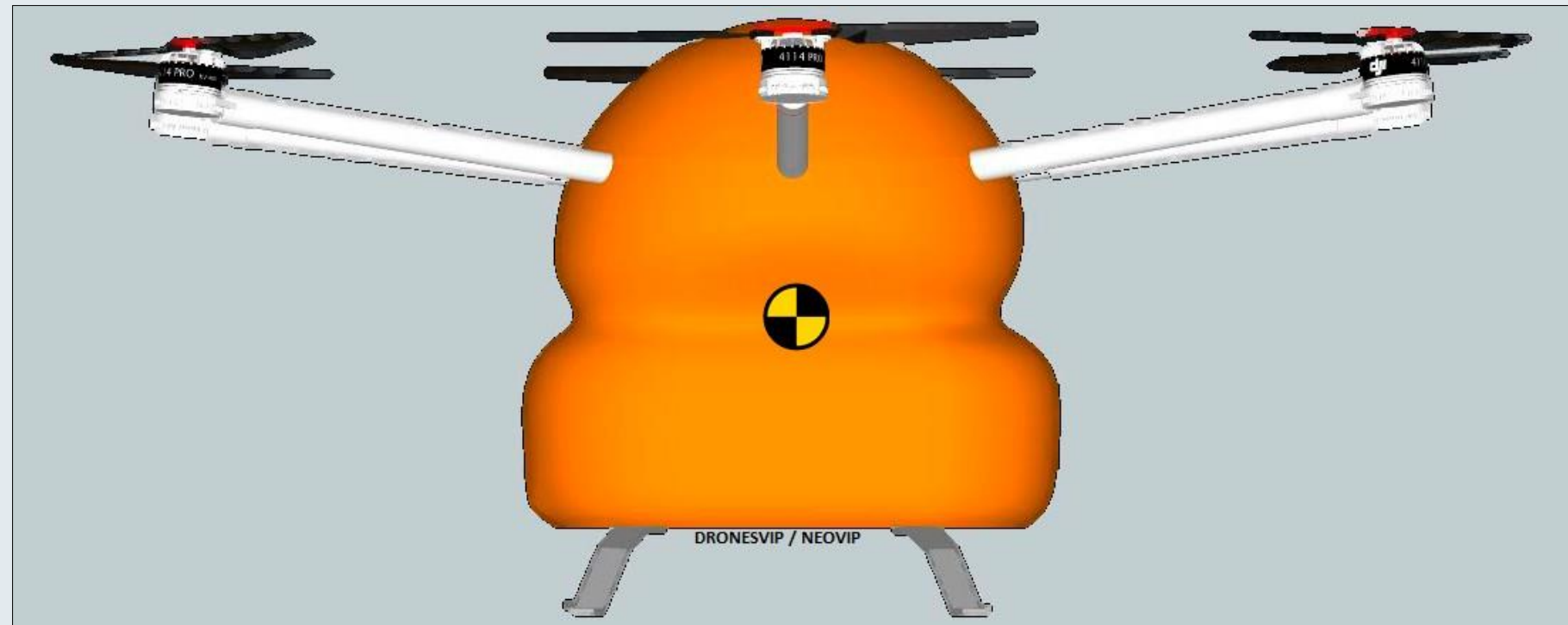


# Influence of the loads and his distribution about the performance and he control of the UAV



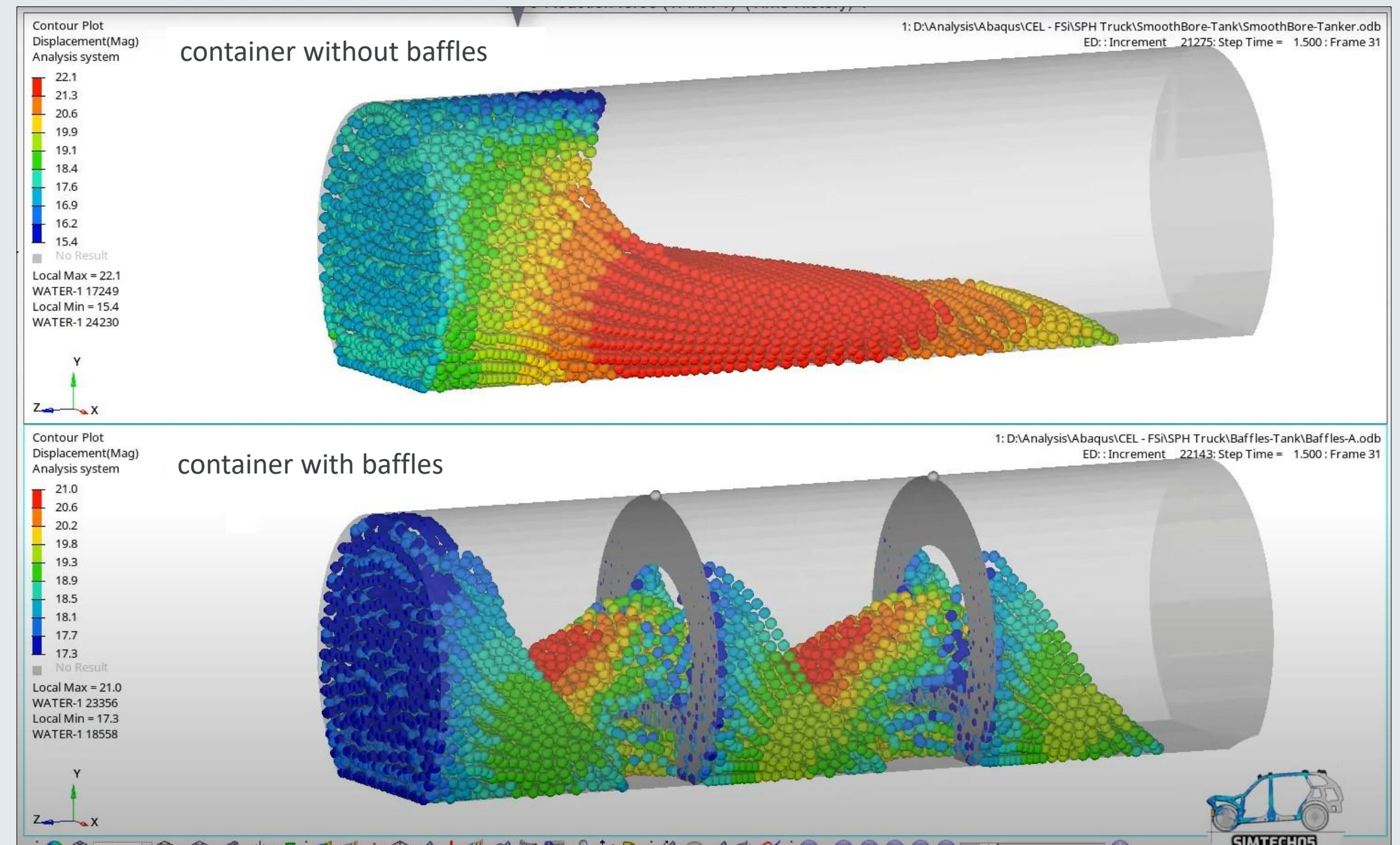
Performance Dispatch		Chapter PD			
Enroute		Section 31			
Long Range Cruise Maximum Operating Altitude					
Max Cruise Thrust					
ISA + 10°C and Below					
WEIGHT (1000 KG)	OPTIMUM ALT (FT)	30000	32000	34000	36000
85	30300	28000	30000	32000	34000
80	31600	29000	31000	33000	35000
75	33000	30000	32000	34000	36000
70	34500	31000	33000	35000	37000
65	36000	32000	34000	36000	38000
60	37700	33000	35000	37000	39000
55	39500	34000	36000	38000	40000
50	41000	35000	37000	39000	41000
45	41000	36000	38000	40000	42000
40	41000	37000	39000	41000	43000

# Influence of the loads and his distribution about the performance and he control of the UAV







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# Influence of the loads and his distribution about the performance and he control of the UAV



# Class and Category Limitations

Types	Advantages	Disadvantages	Example
<b>Fixed wing</b>	Long range Endurance	Horizontal take-off, requiring substantial space or support Inferior maneuverability compared to VTOL (Vertical Take-Off and Landing)	
<b>Tilt wing</b>	Combination of fixed wing and VTOL advantages	Expensive Technology complex	
<b>Unmanned Helicopter</b>	VTOL Maneuverability High payloads possible	Expensive Comparably high maintenance requirements	
<b>Multicopter</b>	Inexpensive, Low weight Easy to launch	Limited payloads Susceptible to wind due to low weight	



# THANKS

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